

# **NC Joining Module NCFB**

# with Cost Optimized Standard Design

The joining module Type 2160A... (in two size available) with integral piezoelectric force sensor and measuring ranges of 5 ... 50 kN is for force-displacement assembly and joining processes. This extremely economically priced NC joining module NCFB allows the user to implement standard joining processes cost-effectively using electromechanical joining modules.

- · Force feedback control
- Direction of measurement: compression
- · Integral charge amplifier
- High measuring accuracy in two ranges
- High rigidity
- High level of sensor overload protection

# Description

The NC joining module Type 2160A... consists of a robust case with integral piezoelectric force sensor. Its motor has an absolute encoder for exact positioning. The compression forces acting on the sensor's piezoelectric measuring element generate a proportional electric charge converted by the integral charge amplifier into an analog voltage signal.

The motor of the NC joining module is an electronically commutated AC servo type controlled by a servo electronics to ensure constant rotational and therefore translational speed. Standard functions such as block pressing, position pressing and force feedback controlled pressing as well as intermediate positioning are supported.

The NC joining module NCFB can be operated with the IndraDrive servo amplifier in combination with maXYmos NC type 5847A... The communication between IndraDrive and maXYmos NC takes place in real-time via SERCOS III. Several field bus slave interfaces are available onboard for customer controlling. PROFIBUS, PROFINET, EtherNet/IP or even EtherCAT can be used with the maXYmos NC can be used at the customer's choosing. Quality data can be transmitted via the Ethernet interface through different protocols and a visualization via VNC® or a data backup can be performed.





### Application

The NC joining module NCFB Type 2160A... is ideal for use in automated production systems.

Assembly is possible vertically and horizontally. The module can be flanged onto the frame of the production unit. Threaded bores of sufficient strength to hold tools are provided in the ram of the threaded spindle drive (Figure 1 and 2).



IP54

## **Technical Data**

| Dimensions                    | mm   | Fig. 1 and 2     |  |
|-------------------------------|------|------------------|--|
| Assembly options              |      | flange assembly  |  |
| Weight                        |      |                  |  |
| Type 2160A15                  | kg   | 35               |  |
| Type 2160A50                  | kg   | 145              |  |
| Max. tool weight Type 2160A15 |      |                  |  |
| without holding brake1)       | kg   | 10               |  |
| with holding brake1)          | kg   | 50               |  |
| Max. tool weight Type 2160A50 |      |                  |  |
| without holding brake1)       | kg   | 15               |  |
| with holding brake1)          | kg   | 100              |  |
| Holding brake                 | V/A  | 24/0,7           |  |
| Direction of measurement      |      | compression      |  |
| Measuring range               |      |                  |  |
| Type 2160A15                  | kN   | 5, 15            |  |
| Type 2160A50                  | kN   | 25, 50           |  |
| Length of stroke              |      |                  |  |
| Type 2160A15                  | mm   | 200              |  |
| Type 2160A50                  | mm   | 400              |  |
| Practical repeatability       | mm   | 0,01             |  |
| Tool holder                   | mm   | Fig. 1 and 2     |  |
| Max. movement speed           |      |                  |  |
| Type 2160A15                  | mm/s | 250              |  |
| Type 2160A50                  | mm/s | 150              |  |
| Displacement sensor system    |      | absolute encoder |  |
| Resolution                    | mm   | 0,001            |  |
| Force sensor                  |      | piezoelectric    |  |
| Temperature range             | °C   | 10 40            |  |

| Linearity in all ranges         | %FSO                     | ≤1                        |  |  |
|---------------------------------|--------------------------|---------------------------|--|--|
| Accuracy class force sensor     | %                        | 0,5                       |  |  |
| Service life of spindle         |                          |                           |  |  |
| (acc. to defined drive profile) | cycles                   | approx. 5 million         |  |  |
| Short stroke                    |                          |                           |  |  |
| Type 2160A15                    | mm                       | ≤70                       |  |  |
| Type 2160A50                    | mm                       | ≤120                      |  |  |
| Lubrication connection          |                          | standard-                 |  |  |
| (internal)                      |                          | lubrication nipple        |  |  |
|                                 |                          |                           |  |  |
| Servo amplifier <sup>2)</sup>   | Bosch-Rexroth Type 2180A |                           |  |  |
| Standard interface              | SERC                     | SERCOS III (internal bus) |  |  |
|                                 |                          |                           |  |  |
| Evaluation unit <sup>3)</sup>   | maXYm                    | maXYmos NC Type 5847A     |  |  |
| Standard interface              | PR                       | PROFIBUS, PROFINET,       |  |  |
|                                 | Et                       | herNet/IP, EtherCAT       |  |  |
| Power supply                    | VDC                      | 24 ±5 %                   |  |  |

Protection class

A bending of the plunger depending on the tool weight must be considered for a horizontal installation.

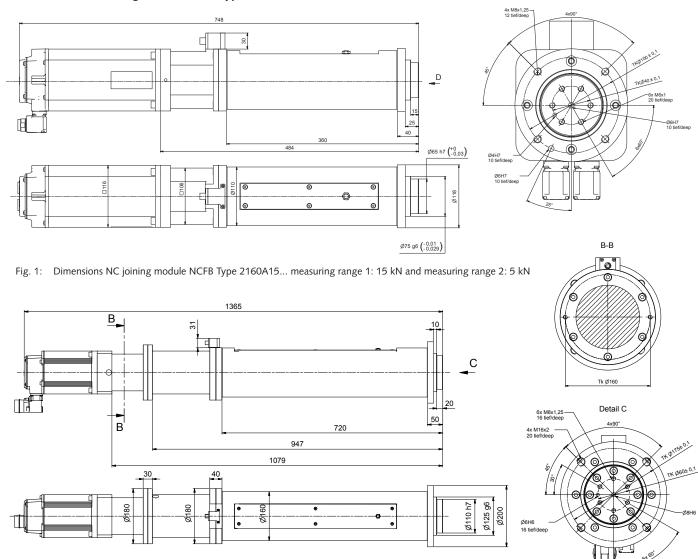
<sup>&</sup>lt;sup>1)</sup> Attention has to be paid to possible radial forces independent of the installation position. Permissible tool weight may have to be reduced for manual feed.

 $<sup>^{\</sup>mbox{\tiny 2)}}$  Servo amplifier see accessories data sheet 003-125 Type 2180A...

<sup>&</sup>lt;sup>3)</sup> Evaluation unit maXYmos NC Type 5847A... see data sheet 003-126



# Dimensions NC Joining Module NCFB Type 2160A...



The radial forces (for example due to the weight of the tool) must be considered for the installation. An external guide may have to be provided for the plunger.

Fig. 2: Dimensions NC joining module NCFB Type 2160A50... measuring range 1: 50 kN and measuring range 2:25 kN



# Functional Principle with maXYmos NC Type 5847A...

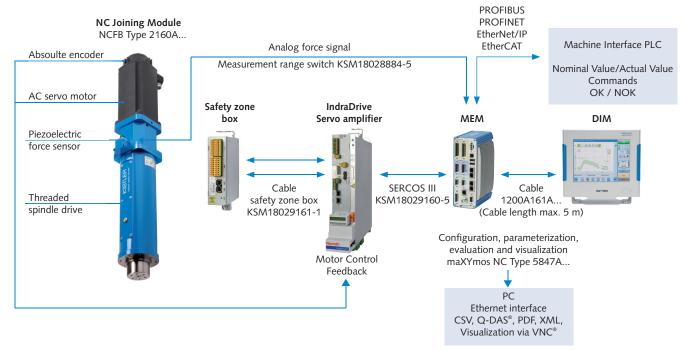


Fig. 3: Functional principle of NC joining system with NC joining module NCFB Type 2160A... and maXYmos NC Type 5847A...

### **Included Accessories**

| • None  |                   | Cable  | Type/Art. No. |
|---|-------------------|--|---------------|
|   |                   | <ul> <li>NCFB 15 motor cable,</li> </ul>             |               |
| Optional Accessories  | Type/Art. No.     | length 5 m RKL4302                                   | KSM341600-5   |
| • Evaluation unit maXYmos NC4) (MEM)                          | 5847A             | <ul> <li>NCFB 50 motor cable,</li> </ul>             |               |
| <ul> <li>Bearing rail adapter for 35 mm</li> </ul>            |                   | length 5 m RKL4306                                   | KSM347990-5   |
| Cap rail including 2 fastening                                |                   | <ul> <li>NCFB MSK Feedback cable,</li> </ul>         |               |
| screws M3x10  | 5700A31           | length 5 m RKG4200                                   | KSM303500-5   |
| <ul> <li>Display module (DIM) with pedestal</li> </ul>        | 5877AZ000         | <ul> <li>maXYmos Force transmitter cable,</li> </ul> |               |
| <ul> <li>Connection cable maXYmos</li> </ul>                  |                   | length 5 m   | KSM18028884-5 |
| MEM on DIM, length 5 m  | 1200A161A5        | <ul> <li>SERCOS III connection cable,</li> </ul>     |               |
| Servo amplifier <sup>2)</sup>                                 | 2180A             | length 5 m   | KSM18029160-5 |
|   |                   | <ul> <li>Safety zone box cable,</li> </ul>           |               |
| <sup>2)</sup> Servo amplifier Type 2180A see accessory data s |                   | 2 cables required), length 1 m                       | KSM18029161-1 |
| 4) Evaluation unit maXYmos NC Type 5847A see d                | ata sheet 003-126 | • -  |               |

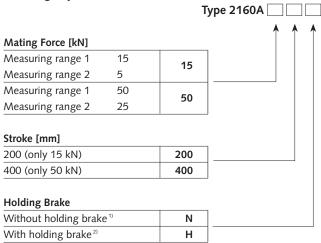
# Ordering Key Servo Amplifier for NCFB

|           |                       |            | Type 2180A |
|-----------|-----------------------|------------|------------|
| Power se  | ection for NC joining | <b>↑ ↑</b> |            |
| NCFB      | 2160A 15              | NCFB0015   |            |
| NCFB      | 2160A 50              | NCFB0050   |            |
|           |                       |            |            |
| Safety te | chnology              |            |            |
| with safe | ty zone box           | SB         |            |

Other length on request.



# **Ordering Key**



#### Note:

 $^{1)}$  Without holding brake 10 kg at 15 kN

15 kg at 50 kN

<sup>2)</sup> With holding brake 50 kg at 15 kN

100 kg at 50 kN

# Ordering Example

Type 2160A50400N

NC joining module NCFB **Type 2160A...**, measuring range 1: 50 kN, stroke: 400 mm, without holding brake: N.